

Using the NRP to its full potential

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What we're going to do

- Request an account
- Create our own experiment
- Work with the experiment data



Useful links

<http://neurorobotics.net/>

<https://collab.humanbrainproject.eu>

<https://forum.humanbrainproject.eu/c/neurorobotics>



Demo!



Future features

- Direct upload/download of robot models from Blender
- Create experiments from scratch



Create an experiment from scratch


Experiment Filter...



Create New Experiment

Here you can create a new experiment. You can upload your own custom environment, robot, and brain.

 Choose Environment

 Choose Robot

 Choose Brain

 Clone



Distributed Brain Husky Braitenberg experiment

This experiment loads the Husky robot from Clearpath Robotics and the virtual room environment. If the user starts the experiment, the Braitenberg vehicle network is executed and the r...



Create an experiment from scratch

Experiment Filter...

Create
Here you

+

Distributed Brain
This experiment loads
network is executed a

Docked Mouse v
This experiment loads the Mouse in a new world with a fully designed the default walking controller

Choose Environment

- From the Public Environment Library
- From this collab's private library
- From other collab's libraries
- From your local environment

Cancel

nd brain.

ose Brain

er starts the experiment, the Braitenberg vehicle



Get in touch!

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